

# Research Training Workshop 2016

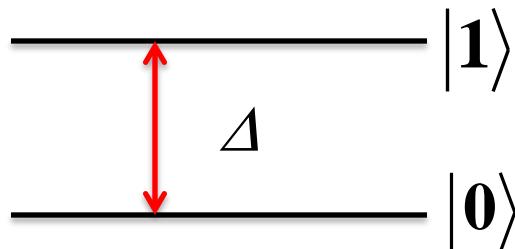
## Quantum Control Lab

### Introduction to decoherence effects

Presenter: NGUYEN LE DUC THINH

*Alexandre Blais, Physical review A 69, 062320 (2004)*  
*K.blum, Density Matrix theory and applications (2012)*  
*Nathan K.Langford, Circuit QED-Lecture Notes (2013)*

# Superposition state



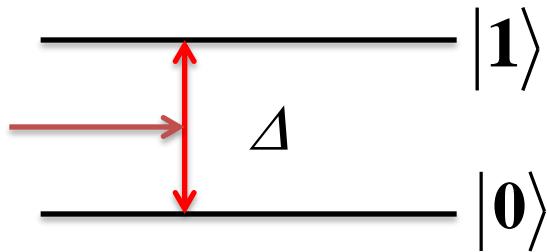
$$H = -\frac{1}{2}\hbar\Delta\sigma_z$$

$$|\psi(0)\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle) \xrightarrow[\substack{H = -\frac{1}{2}\hbar\Delta\sigma_z \\ \text{Free evolution}}]{} |\psi(t)\rangle = \frac{1}{\sqrt{2}}\left(e^{\frac{1}{2}i\Delta t}|0\rangle + e^{-\frac{1}{2}i\Delta t}|1\rangle\right)$$

Stationary states

$$p_0(t) = p_1(t) = \frac{1}{2} \forall t$$

How can we know it was in the superposition state?



$$p_0(t), p_1(t)$$

Oscillating

# Quantum information

Two level system

$$\sigma_x \equiv X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_y \equiv Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \quad \sigma_z \equiv Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$|0\rangle$  and  $|1\rangle$

$$\sigma_x|0\rangle = |1\rangle, \quad \sigma_x|1\rangle = |0\rangle, \quad \sigma_x|\pm\rangle = |\pm\rangle \quad \& \quad \sigma_x|\pm i\rangle = |\mp i\rangle$$

$$|\pm\rangle \equiv (|0\rangle \pm |1\rangle)/\sqrt{2}$$

$$|\pm i\rangle \equiv (|0\rangle \pm i|1\rangle)/\sqrt{2}$$

Superposition states

$$|0\rangle = \frac{1}{\sqrt{2}}(|+\rangle + |-\rangle) = \frac{1}{\sqrt{2i}}(|+i\rangle + |-i\rangle)$$

$$|1\rangle = \frac{1}{\sqrt{2}}(|+\rangle - |-\rangle) = \frac{1}{\sqrt{2i}}(-|i\rangle - |-i\rangle)$$

Suppose Alice want to send Bob information by using two level system states → Bob can know by measure it in the right basis

		Bob					
		$\langle 0  $	$\langle 1  $	$\langle +  $	$\langle -  $	$\langle +i  $	$\langle -i  $
Alice	$ 0\rangle$	100%	0%	50%	50%	50%	50%
	$ 1\rangle$	0%	100%	50%	50%	50%	50%

Other bases: Bob cannot know which state Alice sent

Correlated measurements

# Mixed state

$|0\rangle$  and  $|1\rangle$

$$\sigma_x \equiv X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_y \equiv Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \quad \sigma_z \equiv Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\sigma_x|0\rangle = |1\rangle, \quad \sigma_x|1\rangle = |0\rangle, \quad \sigma_x|\pm\rangle = |\pm\rangle \quad \& \quad \sigma_x|\pm i\rangle = |\mp i\rangle$$

$$|\pm\rangle \equiv (|0\rangle \pm |1\rangle)/\sqrt{2}$$

$$|\pm i\rangle \equiv (|0\rangle \pm i|1\rangle)/\sqrt{2}$$

**Pure states**

		Bob								
		Alice	$\langle 0 $	$\langle 1 $	$\langle + $	$\langle - $	$\langle +i $	$\langle -i $		
ensemble of $ 0\rangle$	$ 0\rangle$	100%	0%	50%	50%	50%	50%	$ \pm i\rangle$		
	$ 1\rangle$	0%	100%	50%	50%	50%	50%	$ \pm i\rangle$		

**Mixed states:** cannot write in a superposition form, or single wave vector

All uncorrelated measurements  $\rightarrow$  Bob cannot know the information in any basis even if Alice tells him which basis she used

# Entanglement

Combined two-level systems quantum states

$$|\mathbf{0}, \mathbf{0}\rangle \text{ or } |\mathbf{1}, \mathbf{1}\rangle \quad |\mathbf{0}, \mathbf{0}\rangle = |\mathbf{0}\rangle \otimes |\mathbf{0}\rangle$$
$$|\mathbf{1}, \mathbf{1}\rangle = |\mathbf{1}\rangle \otimes |\mathbf{1}\rangle$$

Suppose Xavier prepare the above quantum states. Alice and Bob want to know what it is by measure each component separately.

Alice	$\langle 0  $	$\langle 1  $	$\langle +  $	$\langle -  $	$\langle +i  $	$\langle -i  $
$\langle 0  $	50%	0%				
$\langle 1  $	0%	50%				
$\langle +  $			25%	25%		
$\langle -  $			25%	25%		
$\langle +i  $					25%	25%
$\langle -i  $					25%	25%

$$\psi = |\psi_1\rangle \otimes |\psi_2\rangle$$

$$p_{\phi_1\phi_2} = \langle \phi_1 | \psi_1 \rangle \otimes \langle \phi_2 | \psi_2 \rangle$$

There is one basis in which measurements of Bob and Alice are correlated

# Entanglement

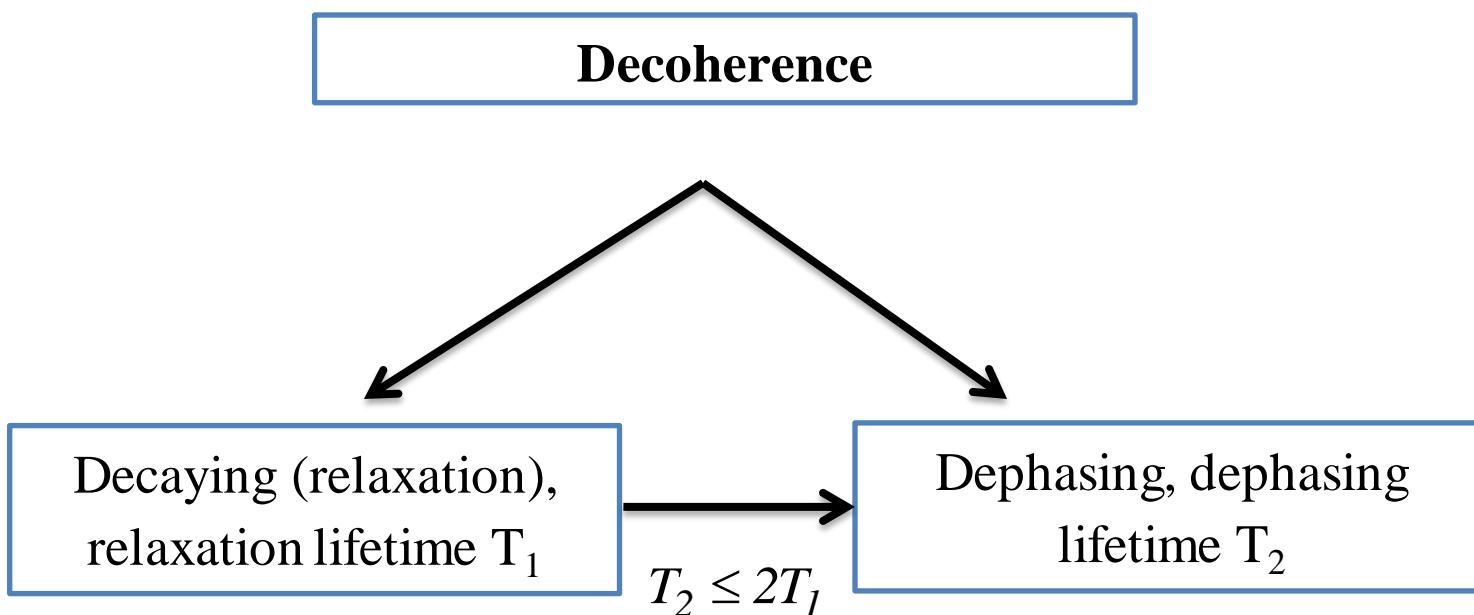
$$|\psi\rangle = \frac{1}{\sqrt{2}} (|0,0\rangle + |1,1\rangle) \equiv |\phi^+\rangle$$

Alice	Bob					
	$\langle 0 $	$\langle 1 $	$\langle + $	$\langle - $	$\langle +i $	$\langle -i $
$ 0\rangle$	50%	0%	25%	25%	25%	25%
$ 1\rangle$	0%	50%	25%	25%	25%	25%
$ +\rangle$	25%	25%	50%	0%	25%	25%
$ -\rangle$	25%	25%	0%	50%	25%	25%
$ +i\rangle$	25%	25%	25%	25%	0%	50%
$  -i\rangle$	25%	25%	25%	25%	50%	0%

There are **three bases** in which measurements of Bob and Alice are correlated

→ **Entanglement states**

# Decoherence

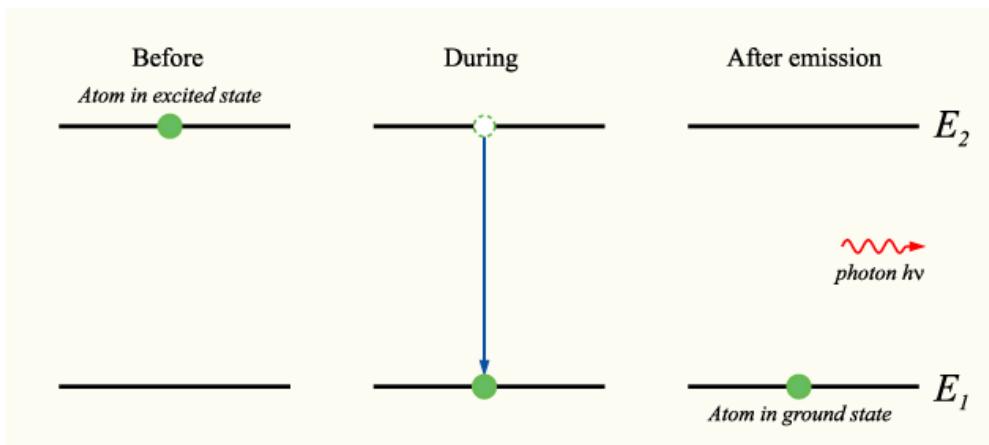


# Decaying

Losing energy to the environment

Probability finding the system in excited state

$$p_1(t) = e^{-\gamma t} \rightarrow T_1 = \frac{1}{\gamma}$$



# Dephasing

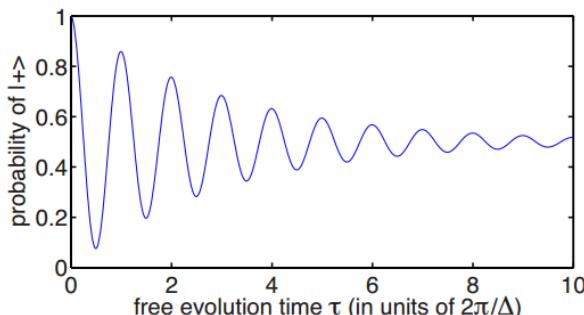
$$|\psi(0)\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle) \xrightarrow[H = -\frac{I}{2}\hbar\Delta\sigma_z]{} |\psi(t)\rangle = \frac{1}{\sqrt{2}}\left(e^{\frac{I}{2}i\Delta t}|0\rangle + e^{-\frac{I}{2}i\Delta t}|1\rangle\right)$$

$$|+\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$$

$$p_+(t) = \langle + | \psi(t) \rangle = \frac{1}{2} + \frac{1}{2} \cos(\Delta t)$$

$$|\psi(0)\rangle = \frac{1}{\sqrt{2}}(|0\rangle + e^{-i\phi}|1\rangle) \xrightarrow[+]{} p_+(t) = \langle + | \psi(t) \rangle = \frac{1}{2} + \frac{1}{2} \cos(\Delta t - \phi)$$

Random phase kick  
from environment



Average measurements

$$p_+(t) = \frac{1}{2} + \frac{1}{2} \cos(\Delta t - \phi/2) \cos(\phi/2)$$

Reduced amplitude

# Treatment of decoherence

Density matrix

Pure state

$$\rho = |\chi\rangle\langle\chi|$$

Mix state

$$\rho = W_a |\chi_a\rangle\langle\chi_a| + W_b |\chi_b\rangle\langle\chi_b| + \dots$$

Pure state 2-level system

$$|\chi\rangle = a_1 |0\rangle + a_2 |1\rangle$$

$$\rho = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \begin{pmatrix} a_1^* & a_2^* \\ a_2^* & a_1^* \end{pmatrix} = \begin{pmatrix} |a_1|^2 & a_1 a_2^* \\ a_1^* a_2 & |a_2|^2 \end{pmatrix}$$

$$Tr(\rho) = 1$$

$$\langle A \rangle = Tr(\rho A)$$



Diagonal elements: probability to find the system in the pure state.

Relaxation: diagonal element decaying

# Treatment of decoherence

$$|\psi(0)\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle) \xrightarrow[H = -\frac{1}{2}\hbar\Delta\sigma_z]{} |\psi(t)\rangle = \frac{1}{\sqrt{2}}\left(e^{\frac{1}{2}i\Delta t}|0\rangle + e^{-\frac{1}{2}i\Delta t}|1\rangle\right)$$

$$\rho(t) = |\psi(t)\rangle\langle\psi(t)| = \frac{1}{2}\begin{pmatrix} 1 & e^{i\Delta t} \\ e^{-i\Delta t} & 1 \end{pmatrix}$$

Strongly depends of the basis representation!!!

$$p_+(t) = \langle + | \rho(t) | + \rangle = \frac{1}{4}(1 \quad 1)\begin{pmatrix} 1 & e^{i\Delta t} \\ e^{-i\Delta t} & 1 \end{pmatrix}\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{2} + \frac{1}{2}\cos(\Delta t)$$

→ Oscillation (interference) term coming from the off-diagonal elements

→ coherent superposition

$$\rho(t) = \frac{1}{2}(|0\rangle\langle 0| + |1\rangle\langle 1|) = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$$

Mixed state → no coherent element in this basis

# Master equation

Schrodinger equation

$$i\hbar \frac{\partial |\psi(t)\rangle}{\partial t} = H(t)|\psi(t)\rangle$$

$$|\psi(t)\rangle = U(t)|\psi(0)\rangle$$

$$i\hbar \frac{\partial |U(t)\rangle}{\partial t}|\psi(0)\rangle = H(t)U(t)|\psi(0)\rangle$$

$$i\hbar \frac{\partial U(t)}{\partial t} = H(t)U(t)$$

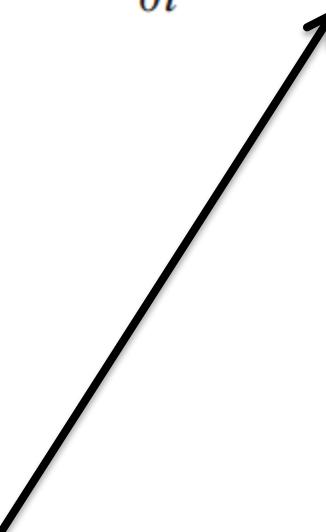
$$\rho(t) = \sum_n W_n |\psi(t)_n\rangle \langle \psi(t)_n|$$

$$= \sum_n W_n U(t) |\psi(0)_n\rangle \langle \psi(0)_n| U(t)^\dagger$$

$$\begin{aligned} i\hbar \frac{\partial \rho(t)}{\partial t} &= i\hbar \frac{\partial U(t)}{\partial t} \rho(0) U(t)^\dagger + i\hbar U(t) \rho(0) \frac{\partial U^\dagger}{\partial t} \\ &= H(t) U(t) \rho(0) U(t)^\dagger - U(t) \rho(0) U(t)^\dagger H(t) \end{aligned}$$

Liouville equation

$$i\hbar \frac{\partial \rho(t)}{\partial t} = [H(t), \rho(t)]$$



# Master equation

Interaction picture

$$H(t) = H_0 + V(t)$$

$$|\psi(t)\rangle = e^{-(i/\hbar)H_0t} |\psi(t)_I\rangle$$

$$|\psi(t)_I\rangle = e^{(i/\hbar)H_0t} U(t) |\psi(0)\rangle$$

$$V(t)_I = e^{(i/\hbar)H_0t} V(t) e^{-(i/\hbar)H_0t}$$

$$\rho(t) = (e^{-(i/\hbar)H_0t}) \rho(t)_I e^{+(i/\hbar)H_0t}$$

$$\dot{\rho}(t)_I = -(i/\hbar)[V(t)_I, \rho(0)] - (i/\hbar)^2 \int_0^t dt' [V(t)_I, [V(t')_I, \rho(t')_I]]$$

Liouville equation

$$i\hbar \frac{\partial \rho(t)_I}{\partial t} = [V(t)_I, \rho(t)_I]$$

$$\rho(t)_I = \rho(0)_I - \frac{i}{\hbar} \int_0^t [V(\tau)_I, \rho(\tau)_I] d\tau$$

$$\rho(t)_I = \rho(0)_I - \frac{i}{\hbar} \int_0^t [V(\tau)_I, \rho(0)_I] d\tau$$



# Master equation

$$H_{tot} = H_S + H_R + H_{SR}(t)$$

$$H_{SR}(t) = V(t) \quad \rho(t) = \underset{R}{Tr} \rho_{tot}(t)$$

$$\dot{\rho}_I(t) = \frac{-i}{\hbar} \underset{R}{Tr} [H_{SR,I}(t), \rho_{tot,I}(0)] - \left( \frac{i}{\hbar} \right)^2 \int_0^t dt' \underset{R}{Tr} [H_{SR,I}(t), [H_{SR,I}(t'), \rho_{tot,I}(t')]]$$

$$\rho_{tot}(0) = \rho(0) \otimes \rho_R$$

Suppose  $H_{SR}$  has no diagonal elements in the bath basis

$$\underset{R}{Tr} [H_{SR,I}(t), \rho_{tot,I}(0)] = \rho_I(0) \underset{R}{Tr} [H_{SR,I}(t), \rho_R] = 0$$

$$\dot{\rho}_I(t) = - \left( \frac{1}{\hbar} \right)^2 \int_0^t dt' \underset{R}{Tr} [H_{SR,I}(t), [H_{SR,I}(t'), \rho_{tot,I}(t')]]$$

# Master equation

$$\rho_{tot,I}(t') = \rho_I(t') \otimes \rho_R$$

Weak coupling approximation

$$\rho_I(t') \rightarrow \rho_I(t)$$

Markoff approximation

$$\dot{\rho}_I(t) = -\left(\frac{1}{\hbar}\right)^2 \int_0^t dt' \text{Tr}_R \left[ H_{SR,I}(t), [H_{SR,I}(t'), \rho_I(t) \otimes \rho_R] \right]$$

$$H_{SR} = \sum_{\alpha} A_{\alpha} \otimes B_{\alpha} \quad H_{SR}(t) = \sum_{\alpha} A_{\alpha}(t) \otimes B_{\alpha}(t)$$

$$\langle Q \rangle = \text{Tr}_R(\rho Q) \quad \text{Tr}(ABC) = \text{Tr}(CAB)$$

$$\begin{aligned} \langle B_{\alpha}(t) B_{\beta}(t') \rangle &= \text{Tr}_R \left[ e^{\frac{iH_R t}{\hbar}} B_{\alpha} e^{-\frac{iH_R t}{\hbar}} e^{\frac{iH_R t'}{\hbar}} B_{\beta} e^{-\frac{iH_R t}{\hbar}} \rho_R \right] = \text{Tr}_R \left[ e^{\frac{iH_R(t-t')}{\hbar}} B_{\alpha} e^{-\frac{iH_R(t-t')}{\hbar}} B_{\beta} \rho_R \right] \\ &= \langle B_{\alpha}(t-t') B_{\beta}(0) \rangle \end{aligned}$$

# Master equation

$$\langle B_\alpha(t) \rangle = 0 \quad t - t' \gg \tau \quad \langle B_\alpha(t) B_\beta(t') \rangle \simeq \langle B_\alpha(t) \rangle \langle B_\beta(t') \rangle = 0$$

$$t'' = t - t', dt'' = -dt'$$

$$\dot{\rho}_I(t) = -\left(\frac{1}{\hbar}\right)^2 \sum_{\alpha, \beta} \int_0^\infty dt'' \left\{ [A_\alpha(t), A_\beta(t-t'')] \rho_I(t) \right\} \langle B_\alpha(t'') B_\beta(0) \rangle - \left[ A_\alpha(t), \rho_I(t) A_\beta(t-t'') \right] \langle B_\beta(0) B_\alpha(t'') \rangle$$

Superoperator

$$H_{SR} = \sum_{\alpha} A_{\alpha} \otimes B_{\alpha} = \sum_{\alpha} \sum_{\omega} A_{\alpha}(\omega) B_{\alpha}$$

$$[H_S, A_{\alpha}(\omega)] = -\omega A_{\alpha}(\omega) \quad A_{\alpha}(\omega, t) = A_{\alpha}(\omega) e^{-i\omega t}$$

$$[H_S, A_{\alpha}^{\dagger}(\omega)] = +\omega A_{\alpha}^{\dagger}(\omega) \quad H_{SR} = \sum_{\alpha} \sum_{\omega} A_{\alpha}(\omega) B_{\alpha}^{\dagger} = \sum_{\alpha} \sum_{\omega} A_{\alpha}^{\dagger}(\omega) B_{\alpha}$$

# Master equation

$$\dot{\rho}_I(t) = -\left(\frac{1}{\hbar}\right)^2 \sum_{\alpha,\beta} \int_0^\infty dt'' \left\{ \left[ A_\alpha(t), A_\beta(t-t'') \rho_I(t) \right] \langle B_\alpha(t'') B_\beta(0) \rangle - \left[ A_\alpha(t), \rho_I(t) A_\beta(t-t'') \right] \langle B_\beta(0) B_\alpha(t'') \rangle \right\}$$

$H_{SR} = \sum_{\alpha} \sum_{\omega} A_\alpha^\dagger(\omega) B_\alpha$    
  $H_{SR} = \sum_{\beta} \sum_{\omega'} A_\beta(\omega') B_\beta^\dagger$    
  $H_{SR} = \sum_{\alpha} \sum_{\omega} A_\alpha(\omega) B_\alpha^\dagger$    
  $H_{SR} = \sum_{\beta} \sum_{\omega'} A_\beta^\dagger(\omega') B_\beta$

$$\dot{\rho}_I(t) = \left(\frac{1}{\hbar}\right)^2 \sum_{\omega,\omega'} e^{i(\omega-\omega')t} \sum_{\alpha,\beta} \Gamma_{\alpha\beta}(\omega') \left[ A_\beta(\omega') \rho_I(t) A_\alpha^\dagger(\omega) - A_\alpha^\dagger(\omega) A_\beta(\omega') \rho_I(t) \right] + h.c$$

$$\Gamma_{\alpha\beta}(\omega') = \int_0^\infty dt'' e^{i\omega' t''} \langle B_\alpha(t'') B_\beta^\dagger(0) \rangle = \int_0^\infty dt e^{i\omega' t} \langle B_\alpha(t) B_\beta^\dagger(0) \rangle$$

$$\begin{aligned} \dot{\rho}_I(t) &= \left(\frac{1}{\hbar}\right)^2 \sum_{\omega,\omega'} \sum_{\alpha,\beta} \Gamma_{\alpha\beta}(\omega') \left[ A_\beta(\omega',t) \rho_I(t) A_\alpha^\dagger(\omega,t) - A_\alpha^\dagger(\omega,t) A_\beta(\omega',t) \rho_I(t) \right] \\ &\quad + \left(\frac{1}{\hbar}\right)^2 \sum_{\omega,\omega'} \sum_{\alpha,\beta} \Gamma_{\beta\alpha}^*(\omega') \left[ A_\alpha(\omega,t) \rho_I(t) A_\beta^\dagger(\omega',t) - \rho_I(t) A_\beta^\dagger(\omega',t) A_\alpha(\omega',t) \right] \end{aligned}$$

# Master equation

$$\dot{\rho}_I(t) = \left(\frac{1}{\hbar}\right)^2 \sum_{\omega, \omega'} \sum_{\alpha, \beta} \Gamma_{\alpha\beta}(\omega') \left[ A_\beta(\omega', t) \rho_I(t) A_\alpha^\dagger(\omega, t) - A_\alpha^\dagger(\omega, t) A_\beta(\omega', t) \rho_I(t) \right]$$

$$+ \left(\frac{1}{\hbar}\right)^2 \sum_{\omega, \omega'} \sum_{\alpha, \beta} \Gamma_{\beta\alpha}^*(\omega') \left[ A_\alpha(\omega, t) \rho_I(t) A_\beta^\dagger(\omega', t) - \rho_I(t) A_\beta^\dagger(\omega', t) A_\alpha(\omega, t) \right]$$

$$\Gamma_{\alpha\beta}(\omega') = \frac{1}{2} \gamma_{\alpha\beta}(\omega') + i S_{\alpha\beta}(\omega')$$

$$\Gamma_{\beta\alpha}^*(\omega') = \frac{1}{2} \gamma_{\alpha\beta}(\omega') - i S_{\alpha\beta}(\omega')$$

$$\dot{\rho}_I(t) = -i \left(\frac{1}{\hbar}\right)^2 \sum_{\omega, \omega'} \sum_{\alpha, \beta} S_{\alpha\beta}(\omega') \left[ A_\alpha^\dagger(\omega, t) A_\beta(\omega', t), \rho_I(t) \right]$$

$$+ \left(\frac{1}{\hbar}\right)^2 \sum_{\omega, \omega'} \sum_{\alpha, \beta} \gamma_{\alpha\beta}(\omega') \left[ A_\beta(\omega', t) \rho_I(t) A_\alpha^\dagger(\omega, t) - \frac{1}{2} \{ A_\alpha^\dagger(\omega, t) A_\beta(\omega', t), \rho_I(t) \} \right]$$

# Master equation

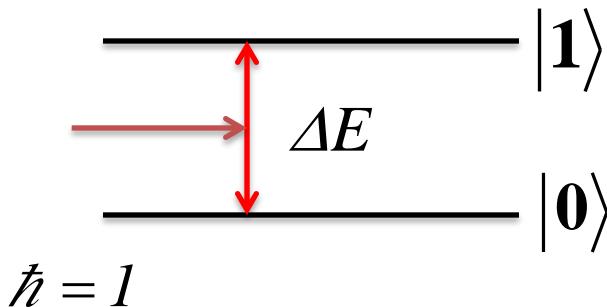
$$\begin{aligned}\dot{\rho}_I(t) = & -i\left(\frac{1}{\hbar}\right)^2 \sum_{\omega,\omega'} \sum_{\alpha,\beta} S_{\alpha\beta}(\omega') \left[ A_\alpha^\dagger(\omega,t) A_\beta(\omega',t), \rho_I(t) \right] \\ & + \left(\frac{1}{\hbar}\right)^2 \sum_{\omega,\omega'} \sum_{\alpha,\beta} \gamma_{\alpha\beta}(\omega') \left[ A_\beta(\omega',t) \rho_I(t) A_\alpha^\dagger(\omega,t) - \frac{1}{2} \left\{ A_\alpha^\dagger(\omega,t) A_\beta(\omega',t), \rho_I(t) \right\} \right]\end{aligned}$$

$$\omega \neq \omega' \tau_S = \frac{1}{|\omega - \omega'|} \gg \tau \rightarrow \omega \approx \omega'$$

Master equation in Schrodinger Picture

$$\begin{aligned}\dot{\rho}(t) = & -i[H_S, \rho] - i\left(\frac{1}{\hbar}\right)^2 \sum_{\omega} \sum_{\alpha,\beta} S_{\alpha\beta}(\omega) \left[ A_\alpha^\dagger(\omega) A_\beta(\omega), \rho(t) \right] \\ & + \left(\frac{1}{\hbar}\right)^2 \sum_{\omega} \sum_{\alpha,\beta} \gamma_{\alpha\beta}(\omega) \left[ A_\beta(\omega) \rho(t) A_\alpha^\dagger(\omega) - \frac{1}{2} \left\{ A_\alpha^\dagger(\omega) A_\beta(\omega), \rho(t) \right\} \right]\end{aligned}$$

# Master equation



$$\sigma^+ = |\mathbf{0}\rangle\langle\mathbf{1}| \quad \sigma^- = |\mathbf{1}\rangle\langle\mathbf{0}|$$

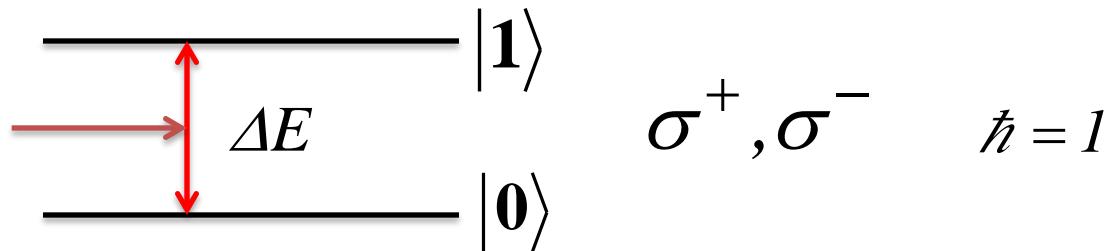
The system interacts with the environment

$$\dot{\rho}_I(t) = -iS[\sigma^+\sigma^-, \rho_I(t)] + \gamma \left[ \sigma^-\rho_I(t)\sigma^+ - \frac{1}{2}(\sigma^+\sigma^-\rho_I(t) + \rho_I(t)\sigma^+\sigma^-) \right]$$

$$\sigma^- = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \sigma^+ = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} \dot{\rho}_{11} & \dot{\rho}_{12} \\ \dot{\rho}_{21} & \dot{\rho}_{22} \end{pmatrix} = \begin{pmatrix} -\gamma\rho_{11} & -iS\rho_{12} - \frac{1}{2}\gamma\rho_{12} \\ iS\rho_{12} - \frac{1}{2}\gamma\rho_{21} & \gamma\rho_{11} \end{pmatrix}$$

# Master equation



$$\left\{ \begin{array}{l} \rho_{11} = 1 - \rho_{22}(0) e^{-\gamma t} \\ \\ \rho_{12} = \rho_{12}(0) \cdot e^{\left(iS - \frac{1}{2}\gamma\right)t} \quad T_2 \leq 2T_1 = \frac{2}{\gamma} \\ \\ \rho_{12} = \rho_{12}(0) \cdot e^{\left(-iS - \frac{1}{2}\gamma\right)t} \\ \\ \rho_{22} = \rho_{22}(0) e^{-\gamma t} \end{array} \right.$$

**THANK YOU FOR  
YOUR LISTENING!**